

# Biographical Reactive Systems

Marino Miculan  
MADS lab  
(with results by many people)

MeMo Workshop, June 6, 2014

## Statics

## Dynamics

## Metatheory & Tools

## Conclusions

### Biographical Reactive System

A discrete *reactive system* is composed by a set of states and a transition relation.

A **Biographical Reactive System** is a RS where

- States are **bigraphs**: data structures rendering explicitly the positions and connections of system's components
- State transitions are **bigraph rewritings** defined by a set of local reaction rules

So BRSS propose as an *operational* metamodel.

# **Bigraphical Reactive Systems**

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# Models for concurrent, distributed systems

Distributed systems are cool, but so damn complex and error prone...

In the last 40 years, TCS have developed hundreds of models and calculi, each focusing on some specific aspects, and providing

- mathematical theories
- prototypes (simulation tools)
- model checkers
- editors
- other nice stuff (even some Right Stuff!)

# Models for concurrent, distributed systems

Models are cool, but still so damn complex and error prone...

- in different models, many definitions and results look almost the same
- everytime we have to start over (almost) from scratch
- Implementing tools is time consuming!

"The final model" does not exist

We have to accept a plethora of specific models

# ***Bigraphs and Bigraphical Reactive Systems***

Introduced by R. Milner et al. (2001) as a formal, graphical **meta-model** for (distributed) systems (but lot of work by many people, since then)

## **Main aims:**

a theoretical framework  
covering many models  
dealing with *localities*  
and *connections*


general results,  
tools and techniques  
which can be readily  
instantiated to  
specific calculi

a common ground  
where different  
models can be  
formally compared  
and merged


Another (unexpected?)  
application:  
a data structure for  
representing *semi-structured  
informations*, like knowledge,  
architectures,...

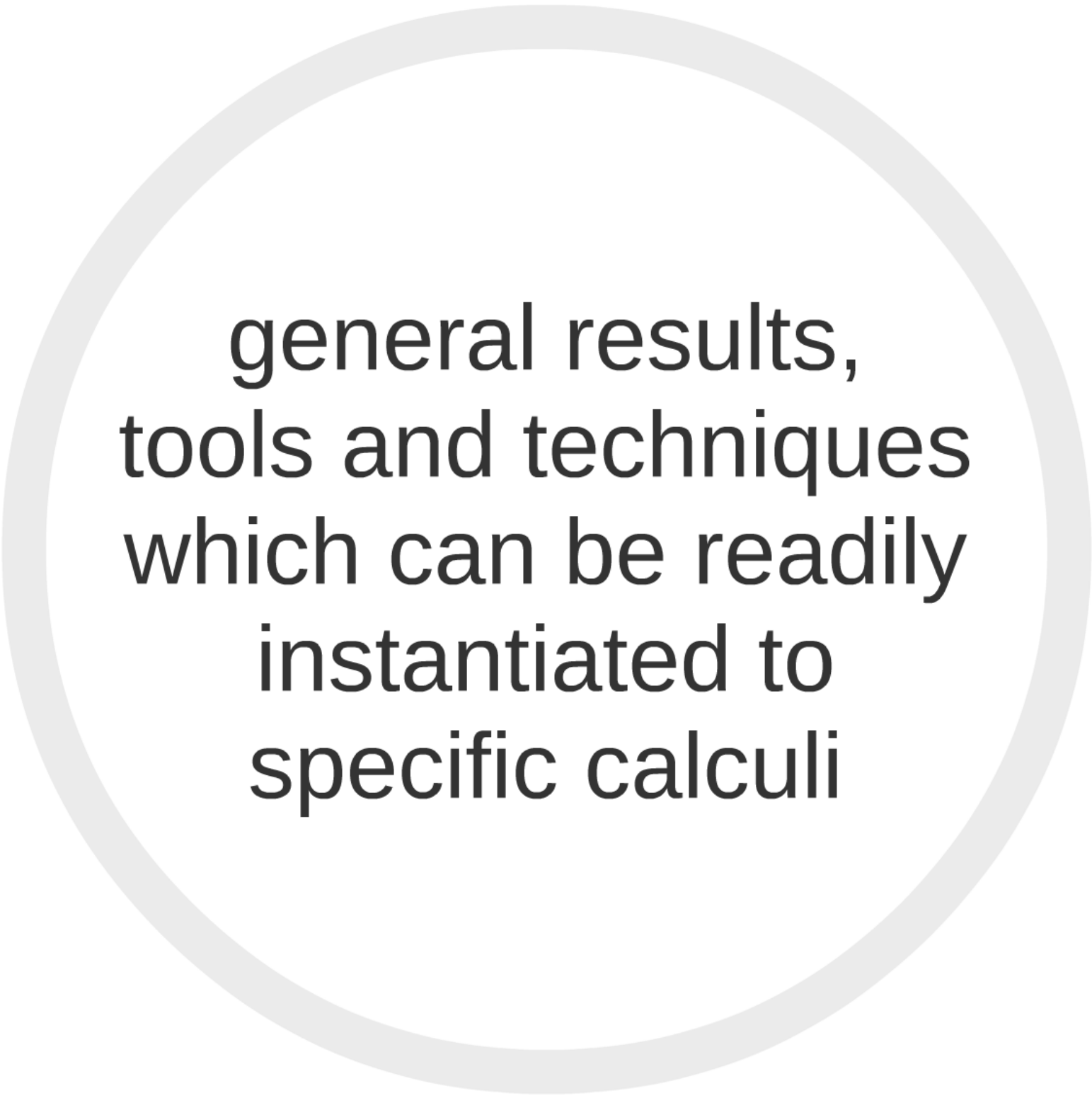
In this tutorial: a gentle (and not very  
abstract) introduction to bigraphs

For more details:  
• Milner's book "The Space and Motion  
of Communicating Agent", 2009  
• [bigraph.org](http://bigraph.org)  
• many other works...

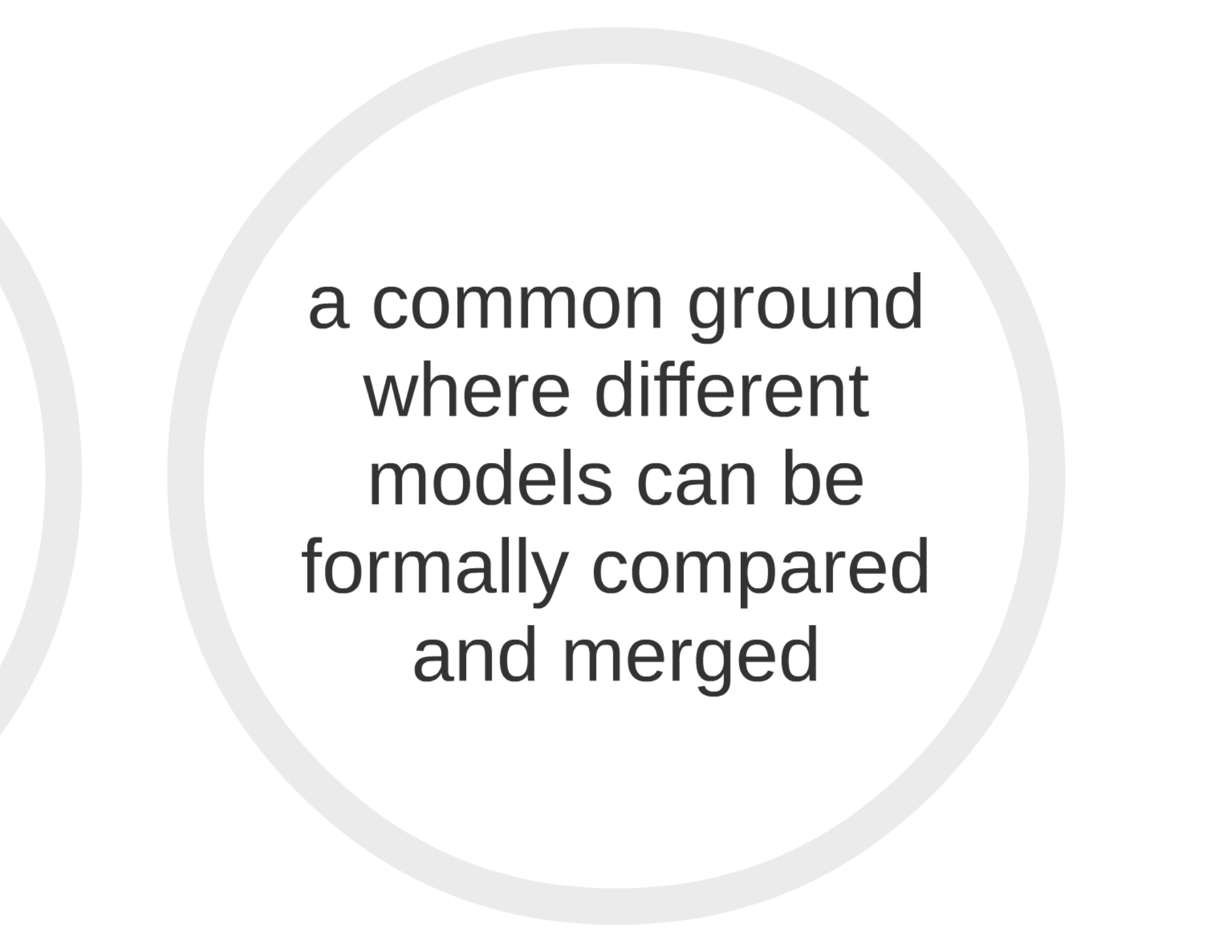


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# Bigraphical Reactive System

A discrete *reactive system* is composed by a set of states and a transition relation.

A **Bigraphical Reactive System** is a RS where

- States are **bigraphs**: data structures rendering explicitly the positions and connections of system's components
- State transitions are **bigraph rewritings** defined by a set of local reaction rules

So BRSs propose as an *operational* metamodel.

# Statics

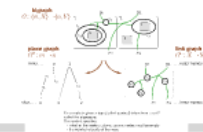
## What's a Bigraph?

A bigraph  $G$  is a pair of graphs on the same (finite) set  $V$  of nodes:  
 the place graph: a forest representing the topology of the system  
 the link graph: a hypergraph representing the connections



## What's a Bigraph?

Compact notation: place graph is represented by nesting nodes, sites are grey holes, and roots (or regions) are outlined



## Anatomy of a Bigraph

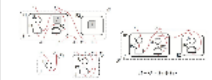
place graph:  $(P, \text{root}, \text{site})$   
 link graph:  $(L, \text{edge}, \text{site})$   
 bigraph:  $(G, \text{root}, \text{site})$   
 A bigraph is an interface

## Horizontal composition of bigraphs (tensor)

Bigraphs can be juxtaposed when interfaces do not share names  
 Given  $G_1 = (P_1, \text{root}_1, \text{site}_1)$  and  $G_2 = (P_2, \text{root}_2, \text{site}_2)$   
 the horizontal composition is  
 $G_1 \otimes G_2 = (P_1 \cup P_2, \text{root}_1 \cup \text{root}_2, \text{site}_1 \cup \text{site}_2)$   
 given by disjoint union of nodes, edges, and maps (parallel with renaming)  
 Notice that  
 1. Order is important:  $G_1 \otimes G_2 \neq G_2 \otimes G_1$   
 2. No links are added between the two systems  
 3. No nodes are merged

## Vertical Composition of bigraphs

Bigraphs can be composed when interfaces are compatible  
 • subbigraph nodes are pushed to sites (for  $\otimes$ )  
 • names are reset to same names



(final is the identity for composition)

## Example: CCS

Original syntax:  $P ::= () \mid a.P \mid \delta.P \mid P \mid Q$

Bigraphs:  
 Signature has two controls: send, recv

Example: encoding of  $\delta.a.m.a.\delta.a.a$



## How to encode a process algebra - syntax

Basic strategy

Process Algebra	Bigraphs
syntactic constructor	control with arity $n$
with $n$ variables	
syntactic tree	place graph
variable	outer name
name	edge

Useful shorthands: nil is just "nothing",  
 (parallel) can be "omitted".

## Example: binding bigraphs

Some ports of controls are marked as binding

Requirement over bigraphs:  
 "all points linked to a binding port of a node  $u$  lie inside  $u$ "

Example: encoding of  $\pi$ -calculus terms



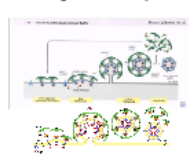
## Sortings

Often, bigraphs generated by a signature are too many.  
 Sorting = discipline for ruling out unwanted bigraphs

sorted bigraphs = well-formed terms  
 unsorted bigraphs = context-free terms

Can be specified in several ways (e.g. predicates in some logic): see work by Hidebrandt, Deloisi, Perrone, ...

## Modeling "informal" systems



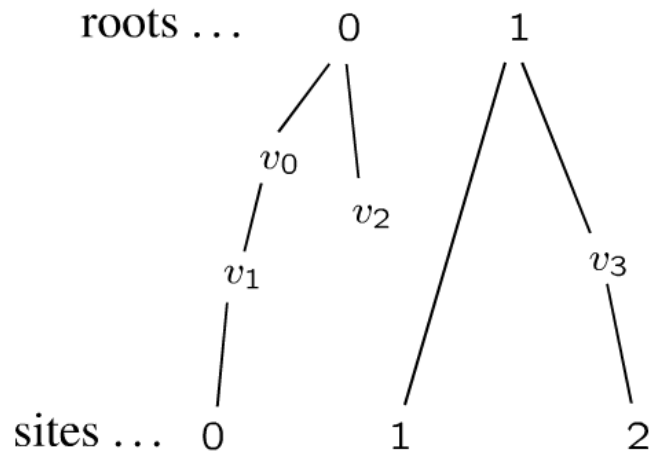
This is a way to give a formal syntax to informal systems

# What's a Bigraph?

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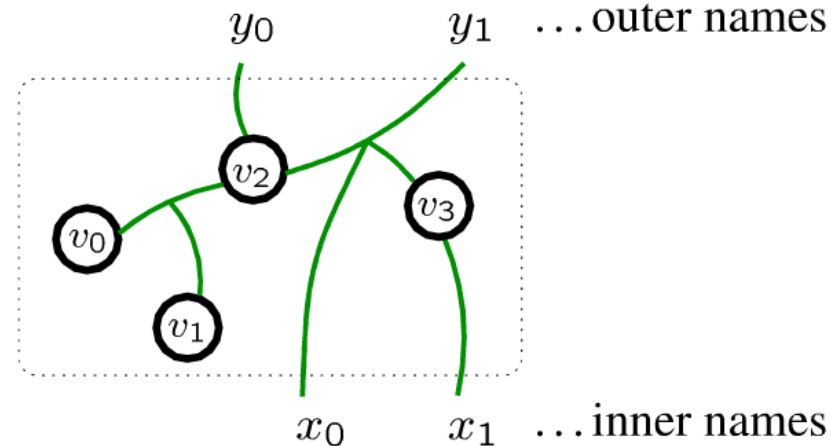
the **place graph**: a forest representing the topology of the system

$$G^P: m \rightarrow n$$



the **link graph**: a hypergraph representing the connections

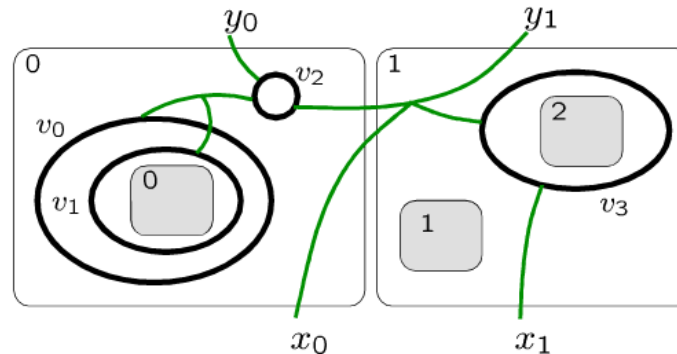
$$G^L: X \rightarrow Y$$



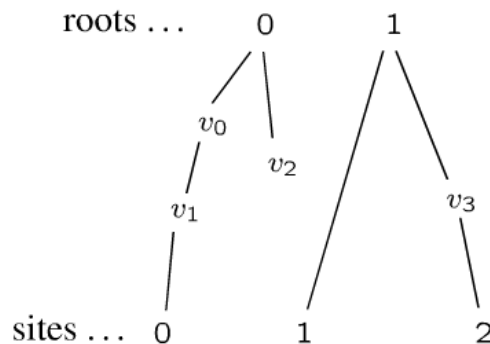
# What's a Bigraph?

Compact notation: place graph is represented by nesting nodes; sites are grey holes, and roots (or regions) are outlined

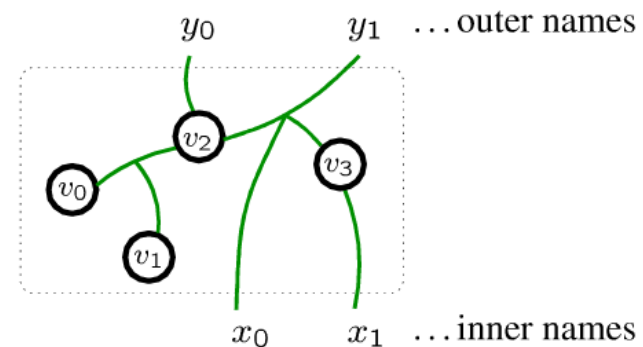
**bigraph**  
 $G: \langle m, X \rangle \rightarrow \langle n, Y \rangle$



**place graph**  
 $G^P: m \rightarrow n$



**link graph**  
 $G^L: X \rightarrow Y$



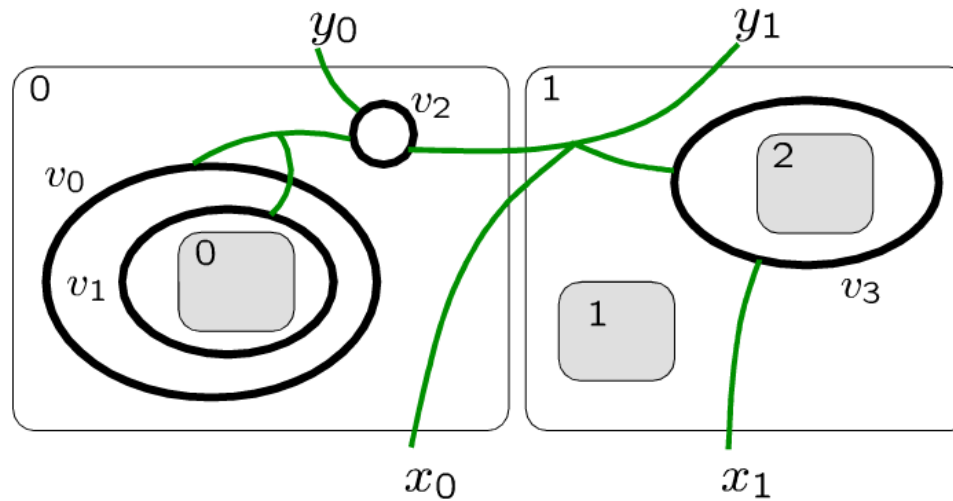
Each node is given a type (called **control**) taken from a set  $\Sigma$  called the **signature**.

The control specifies

- whether the node is *atomic*: atomic nodes must be empty
- the number of *ports* of the node

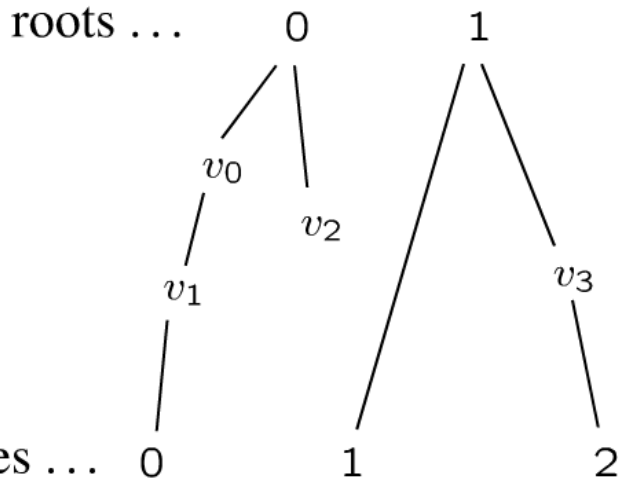
## bigraph

$$G: \langle m, X \rangle \rightarrow \langle n, Y \rangle$$



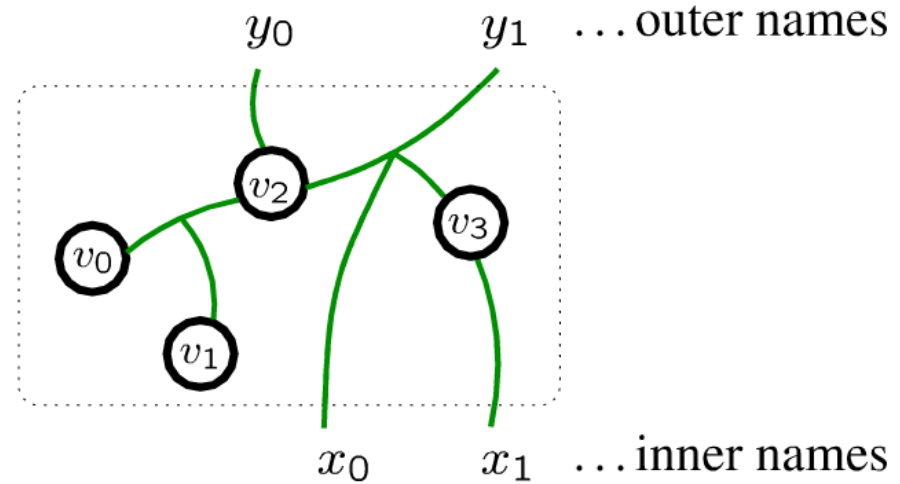
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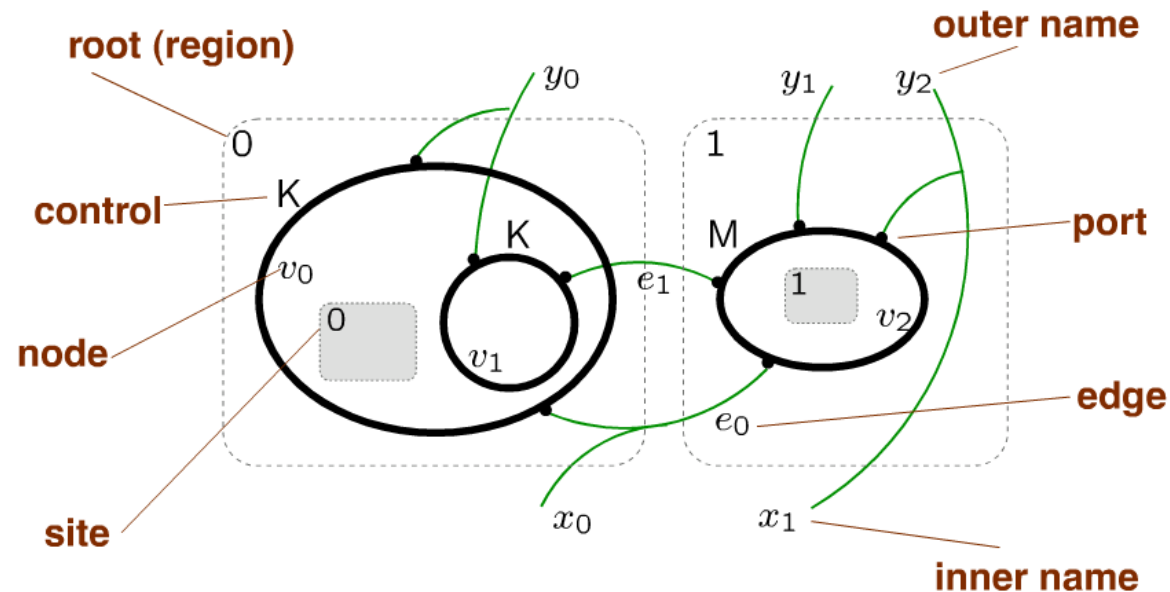


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# Anatomy of a Bigraph



"Bigraphs have a formal graphical language  
 • But complete textual languages (kind of graph grammars) are available  
 • "People want pictures. Coding is for nerds."

**place** = **root** or **node** or **site**

**link** = **edge** or **outer name**

**point** = **port** or **inner name**

$G^P = (V, ctrl, prnt): m \rightarrow n$  (place graph)

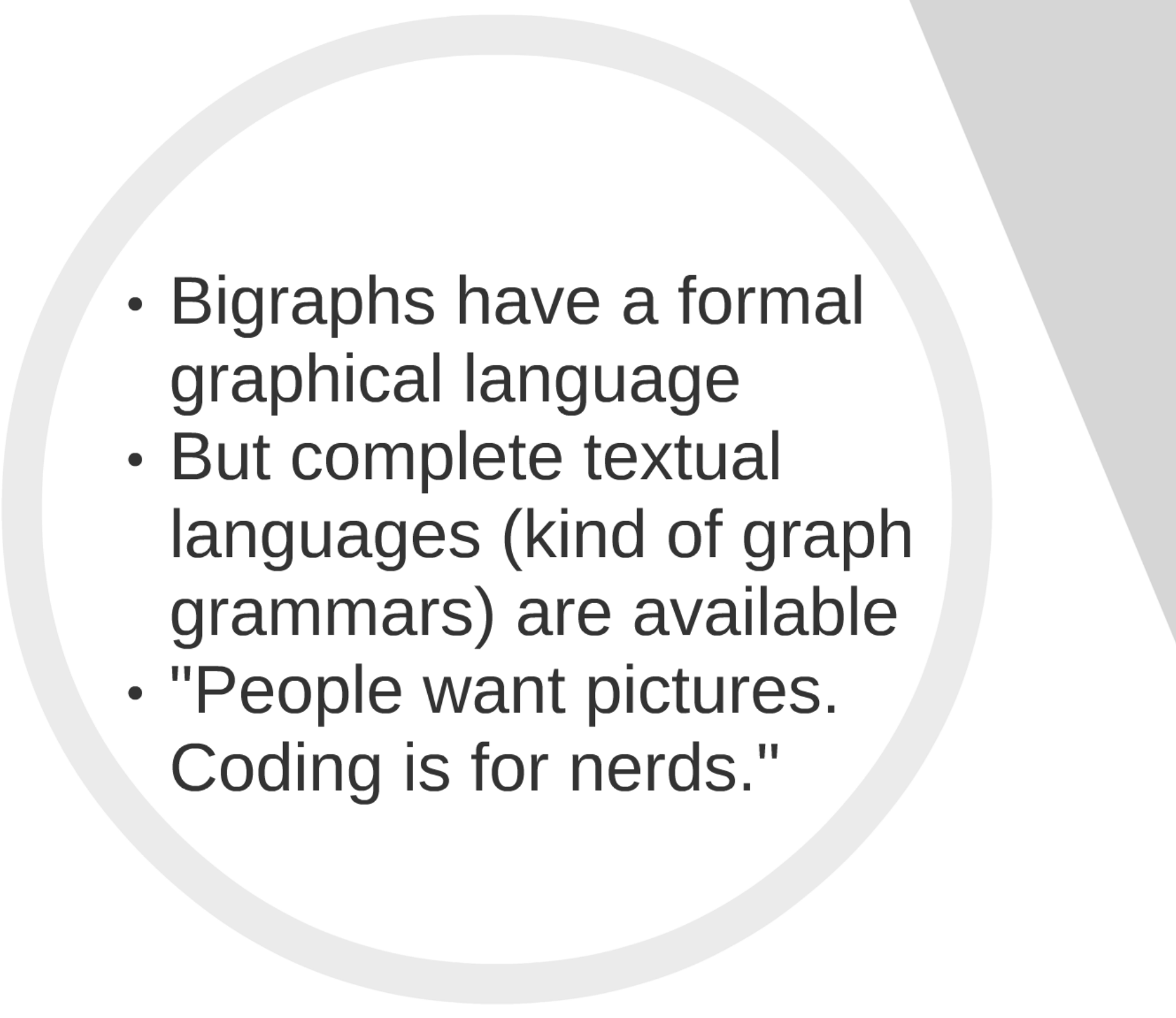
$G^L = (V, E, ctrl, edge, link): X \rightarrow Y$  (link graph)

$G = (V, E, ctrl, edge, prnt, link): \langle m, X \rangle \rightarrow \langle n, Y \rangle$  (bigraph)

$= (G^P, G^L)$

A pair  $\langle m, X \rangle$  is an **interface**



- 
- Bigraphs have a formal graphical language
  - But complete textual languages (kind of graph grammars) are available
  - "People want pictures. Coding is for nerds."

# Horizontal composition of bigraphs (tensor)

Bigraphs can be juxtaposed when interfaces do not share names

Given  $G_1 : \langle m_1, X_1 \rangle \rightarrow \langle n_1, Y_1 \rangle$ ,  $G_2 : \langle m_2, X_2 \rangle \rightarrow \langle n_2, Y_2 \rangle$   
the horizontal composition is

$$G_1 \otimes G_2 : \langle m_1 + m_2, X_1 \uplus X_2 \rangle \rightarrow \langle n_1 + n_2, Y_1 \uplus Y_2 \rangle$$

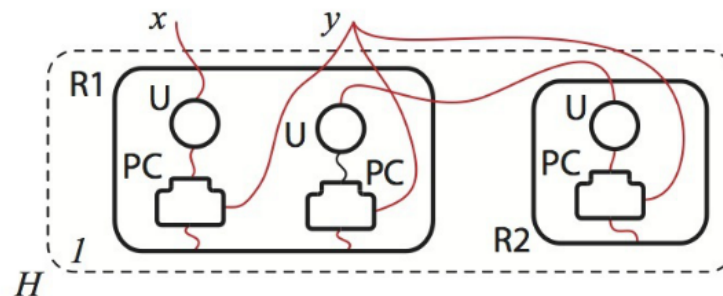
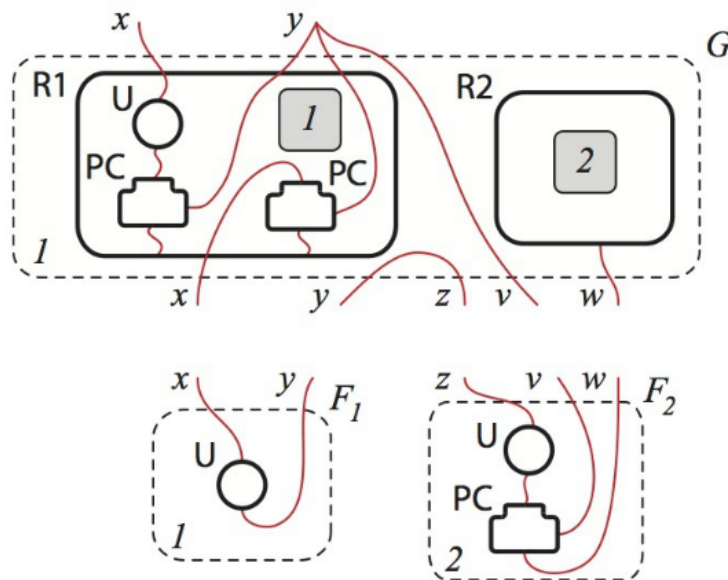
given by disjoint union of nodes, edges, and maps (possibly with renamings).  
Notice that:

1. Order is important:  $G_1 \otimes G_2 \neq G_2 \otimes G_1$
2. No links are added between the two summands
3. No roots are merged

# Vertical Composition of bigraphs

Bigraphs can be composed when interfaces are compatible

- subbigraphs' roots are grafted in sites (holes)
- names are wired to same names



$$H \equiv G \circ (F_1 \otimes F_2)$$

(What is the identity for composition?)

# Bigraphs form a monoidal category

Given a signature  $\Sigma$ ,  $(\text{Big}(\Sigma), \otimes, I)$  is the *monoidal category* where

- objects of  $\text{Big}(\Sigma)$ : interfaces
- morphisms of  $\text{Big}(\Sigma)$ : bigraphs over the signature  $\Sigma$
- composition is vertical composition
- $\otimes$  is horizontal composition

(Categories of place graphs and link graphs can be defined likewise)

Categories of bigraphs are akin Lawvere theories

# How to encode a process algebra - syntax

Basic strategy

## **Process Algebra**

syntactic constructor  
with n variables

syntactic tree

variable

name

## **Bigraphs**

control with arity n

place graph

outer name

edge

Useful shorthands: nil is just "nothing",  
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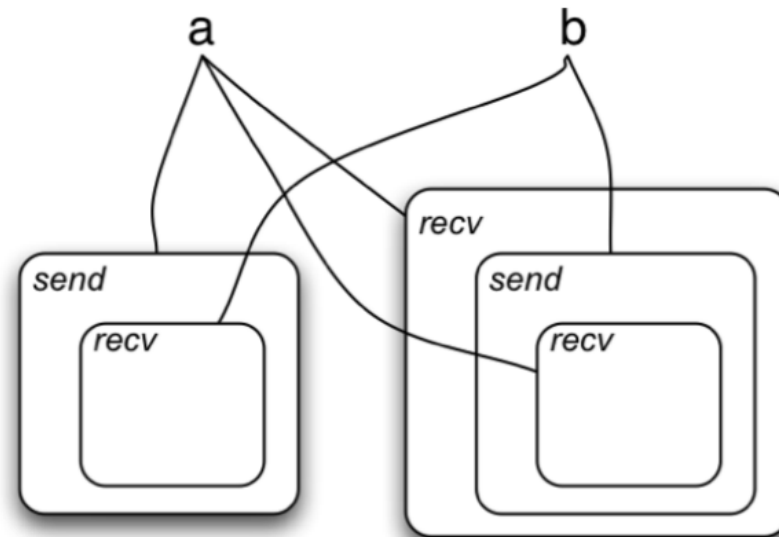
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Original syntax:  $P ::= 0 \mid a.P \mid \bar{a}.P \mid P|Q$

Bigraphs:

Signature has two controls: *send*, *recv*

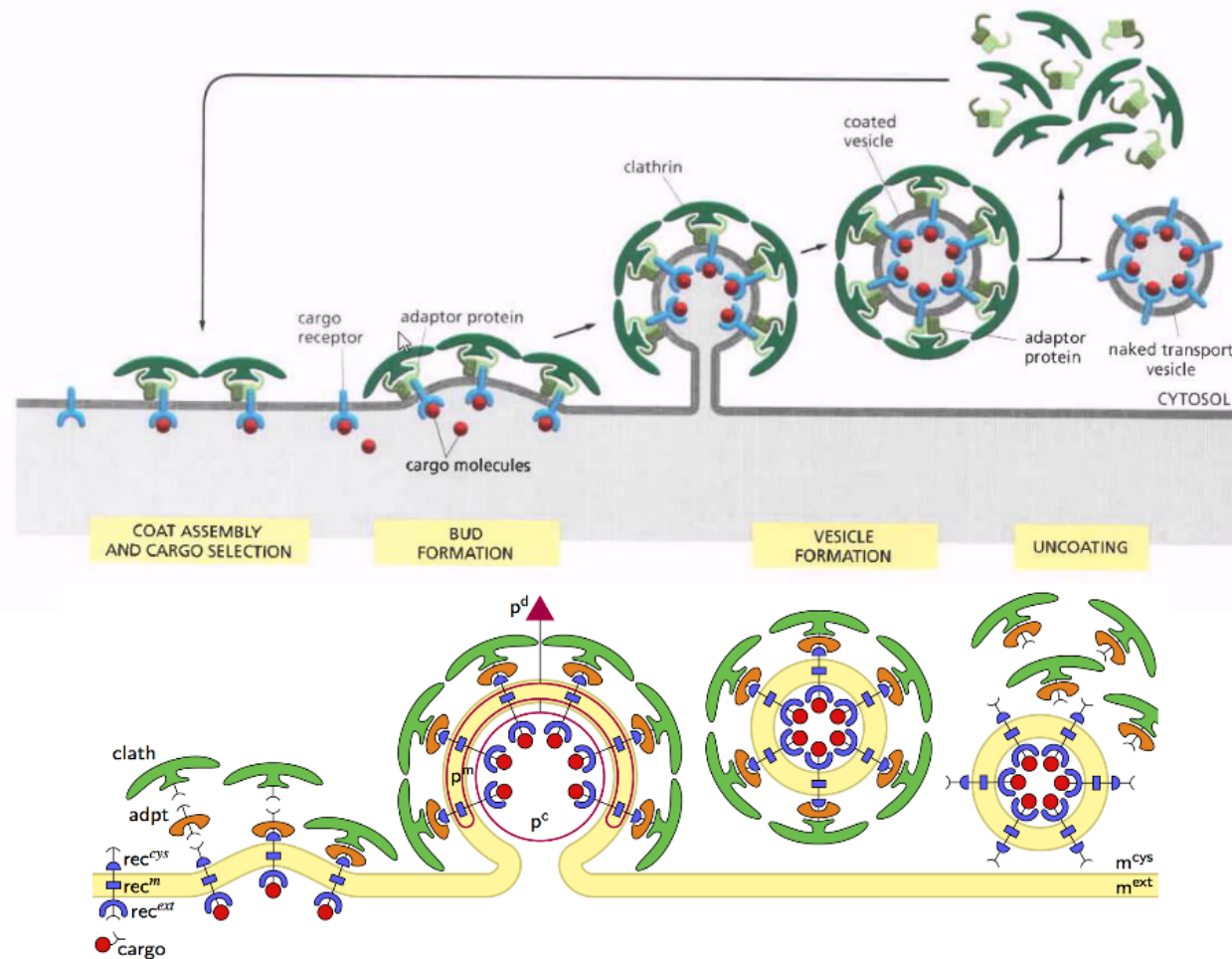
Example: encoding of  $\bar{a}.b.0|a.\bar{b}.a.0$



# Modeling "informal" systems

756 Chapter 13: Intracellular Vesicular Traffic

From Alberts et al.



This is a way to give a formal syntax to informal systems

# Sortings

Often, bigraphs generated by a signature are too many.

**Sorting** = discipline for ruling out unwanted bigraphs

$$\frac{\text{sorted bigraphs}}{\text{unsorted bigraphs}} = \frac{\text{well-formed terms}}{\text{context-free terms}}$$

Can be specified in several ways (e.g. predicates in some logic); see work by Hildebrandt, Debois, Perrone, ...



# Example: binding bigraphs

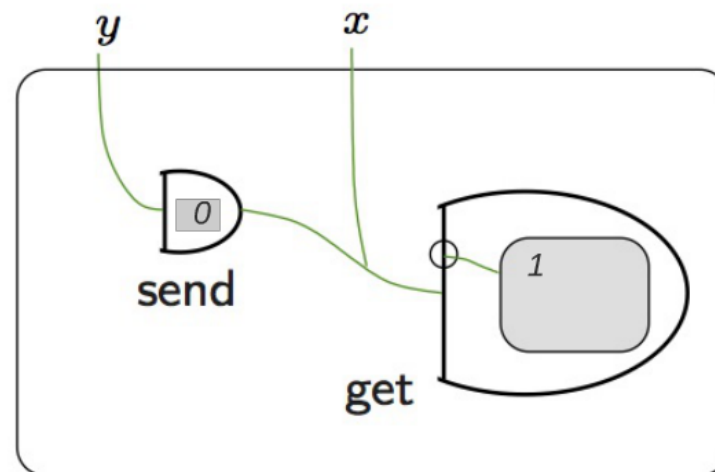
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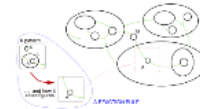
Example: encoding of  $\pi$ -calculus terms

$$\bar{x}y.P \mid x(z).Q$$



# Dynamics

## How does a bigraph evolve?



Graph rewriting: a sub-bigraph (red) is replaced by another (green), with the same outer interface

## Execution policies

Once all matchings have been computed, how to choose that to be applied?

- Bigraphs are agnostic about the rewriting policy; can be non-deterministic, probabilistic, weighted, fair, etc.
- In fact, many variations have been developed. See e.g. Stochastic Bigraphs (for biological purposes).
- Non-interfering reactions can be executed concurrently

## Parametric Reaction rules

Applied to a bigraph  $G$ , a rule  $R$  yields:

$$R(G) = G' \text{ where } G' \text{ is a bigraph with the same outer interface as } G \text{ and the same inner interface as } R.$$

$$G' = G \text{ with } R \text{ applied to } G \text{ (i.e. } G' = G \text{ with } R \text{ applied to } G \text{)}$$

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(Note: The notation  $R(G)$  is used to denote the result of applying a rule  $R$  to a bigraph  $G$ .)

## Matching of bigraphs

In the definition of reaction relations:

$$R \text{ is a reaction relation. } R \text{ is a relation between bigraphs } G \text{ and } G' \text{ such that } G \rightarrow R G'.$$

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Key idea:

- The matching problem: Given an agent  $G$  and a rule with redex  $R$ , find all matchings of  $R$  inside the agent  $G$ .

The matching problem is NP-complete, but it is exponential in the width of redexes, which is fixed for a given bigraph (and usually is 0).

Several algorithms have been proposed (including (Birkedal et al.) graph-based, with reduction to SAT (Boehm et al.), to CSP (Ward et al.).)

## Example reaction rules

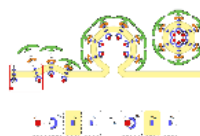
• Rule 1:  $R_1 \rightarrow R_2$  and  $R_2 \rightarrow R_1$



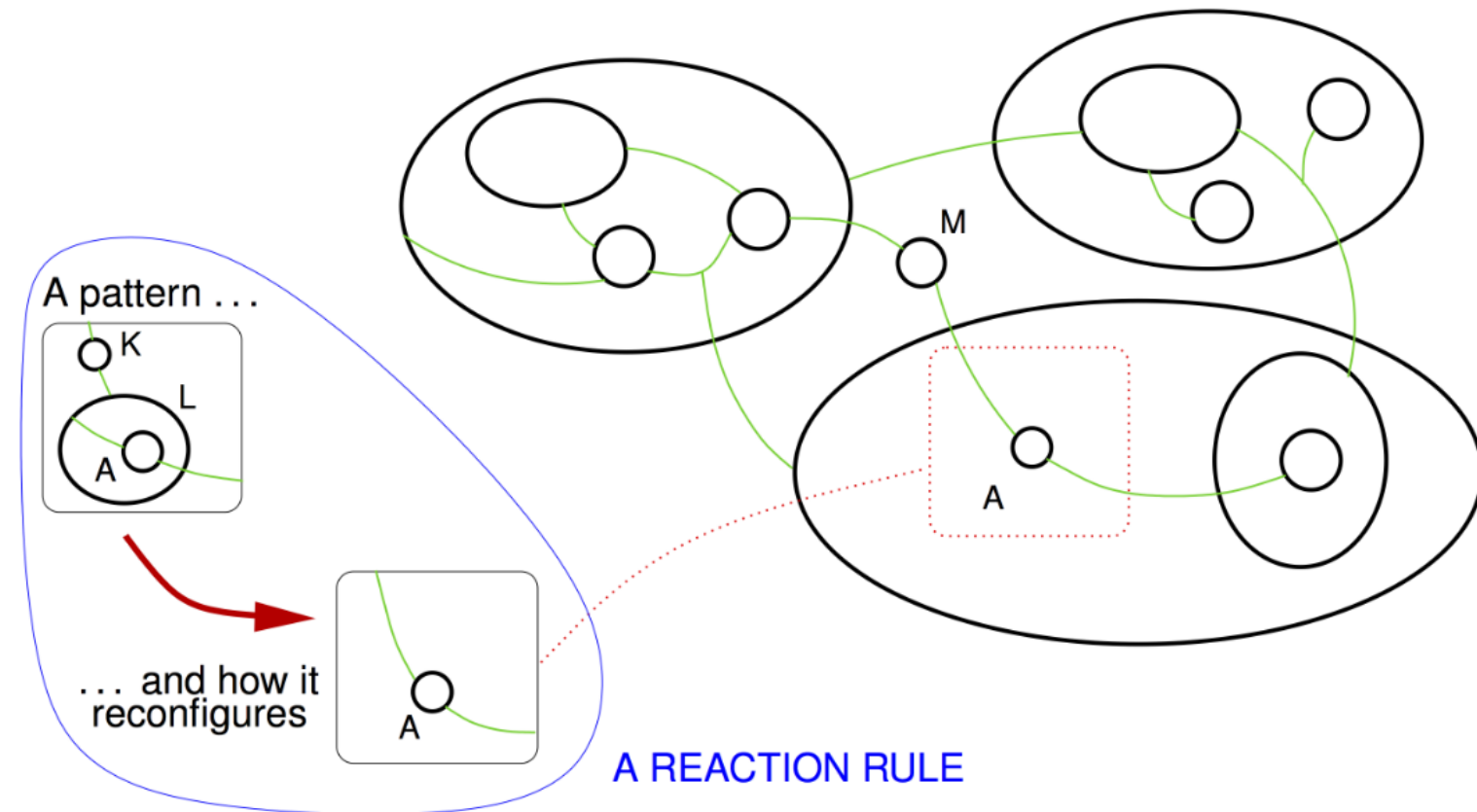
A wide rule: 'long distance' communication



## Example: vesicle formation



# How does a bigraph evolve?



*Graph rewriting*: a sub-bigraph (*redex*) is replaced by another (*reactum*), with the same outer interface

# Parametric Reaction rules

A parametric (reaction) rule has the form

$$(R : \langle m, X \rangle \rightarrow J, R' : \langle n, X \rangle \rightarrow J, \rho : m \rightarrow n)$$

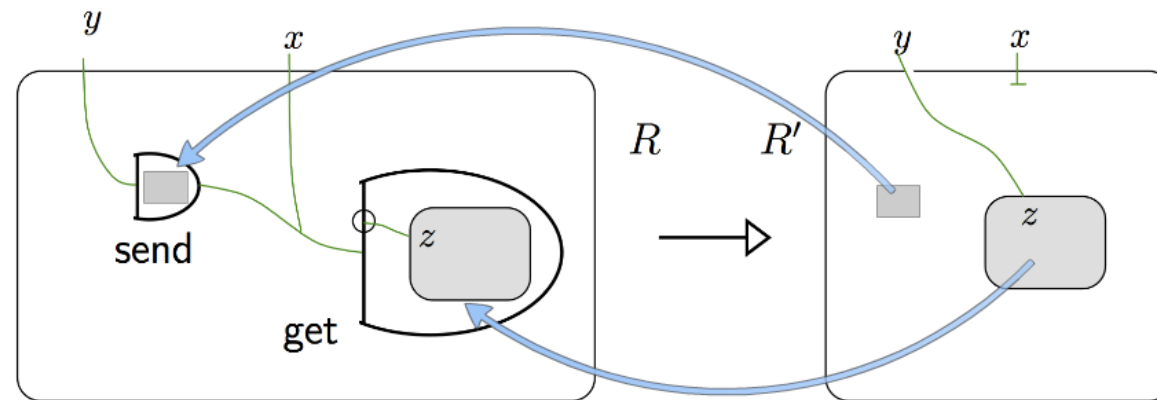
Given a set  $\mathcal{R}$  of reaction rules, the *reaction relation*  $\rightarrow$  is defined by

$$\frac{\begin{array}{l} (R, R', \rho) \in \mathcal{R} \quad D \text{ active} \\ G = D \circ (id_Z \otimes R) \circ \vec{d} \\ G' = D \circ (id_Z \otimes R') \circ \rho(\vec{d}) \end{array}}{G \rightarrow G'}$$

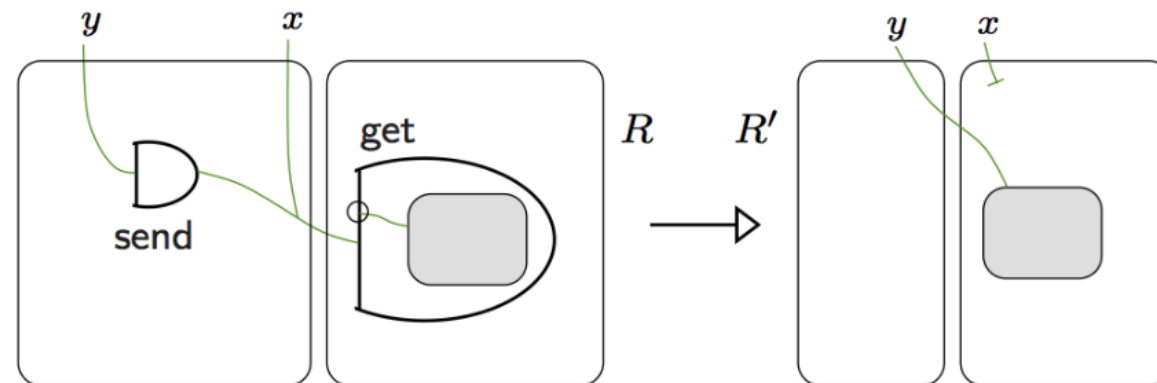
(A context  $D$  is *active* when its sites are only below active nodes.  
Active controls are indicated in the signature.)

# Example reaction rules

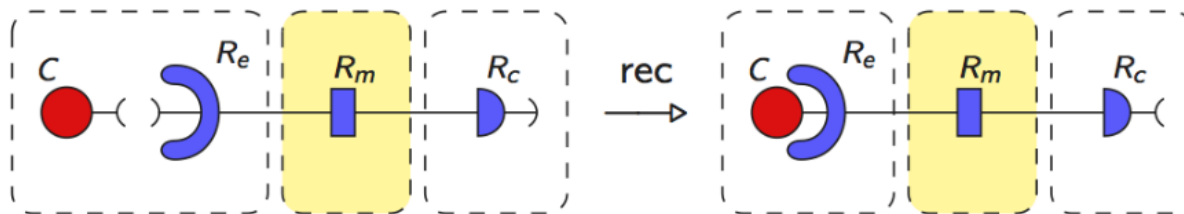
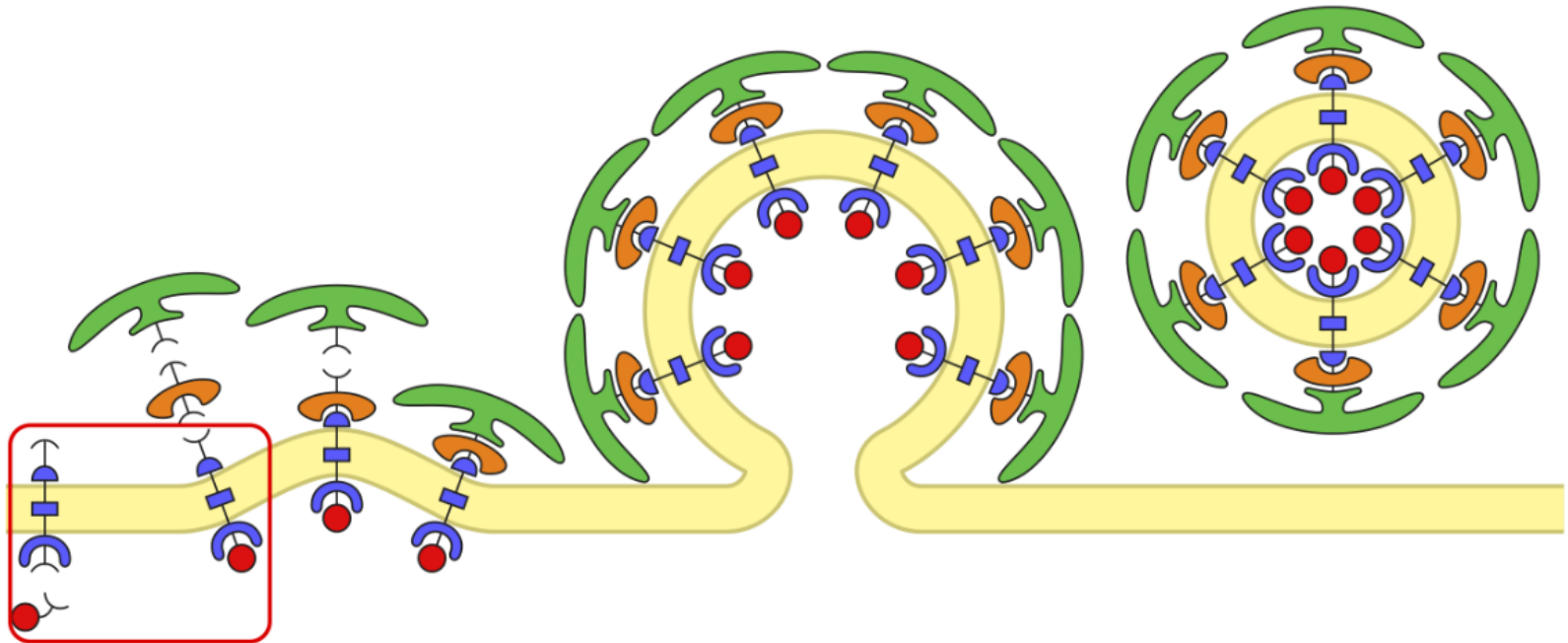
$\pi$ -calculus:  $x\langle y \rangle.P \mid x(z).Q \rightarrow P \mid Q\{y/z\}$



A wide rule: "long distance" communication



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# Matching of bigraphs

In the definition of reaction relations:

$$\frac{\begin{array}{l} (R, R', \rho) \in \mathcal{R} \quad D \text{ active} \\ G = D \circ (id_Z \otimes R) \circ \vec{d} \\ G' = D \circ (id_Z \otimes R') \circ \rho(\vec{d}) \end{array}}{G \rightarrow G'}$$

a key step:

- the **matching problem**: Given an agent  $G$  and a rule with redex  $R$ , find all matchings of  $R$  inside the agent  $G$ .

The matching problem is NP-complete, but it is exponential in the width of redexes, which is fixed for a given BRSs (and usually  $\leq 3$ )

Several algorithms have been proposed (inductive [Birkedal et al.], graph-based, with reduction to SAT [Sevegnani...], to CSP [MP2012]...)

# Execution policies

Once all matchings have been computed, how to choose that to be applied?

- Bigraphs are agnostic about the rewriting policy: can be non-deterministic, probabilistic, weighted, fair, etc.
- In fact, many variations have been developed. See e.g. Stochastic Bigraphs (for biological purposes).
- Non-interfering reactions can be executed concurrently



# Metatheory & Tools

## Deriving a good LTS

Often the semantics of a process algebra is given by means of a Labelled Transition System

$$P \xrightarrow{a} Q$$

Useful for defining bisimilarity, model checking, etc.

**Problem:** how to define a good LTS for a process algebra?

**Goal:** it induces a compositional bisimilarity

$$P \sim Q \text{ iff for all } C[]: C[P] \sim C[Q]$$

In general, it is a difficult and error-prone task.  
(cf. the LTS for mobile ambients)

## LibBig: a Java Library for Bigraphs

An implementation of the machinery for defining and manipulating bigraphical reactive systems. Modeling is implemented as a DSL. Easily extensible and adaptable to other variants.

LibBig is hosted on SourceForge.



## Labels from contexts

In a BRS we can define labels for an agent as the minimal contexts (i.e. bigraphs) which are required to make a reaction

$$C[] \xrightarrow{a} C'[] \text{ if } C[] \text{ is minimal}$$

$C[]$  is "what  $G$  is missing" to make a reaction

In bigraphs, minimality is formally given by the categorical notion of idempotent pushout (IPO).

## Tools

Simulation tools:

- nondeterministic execution engines (BAM [Perrone et al.])
- stochastic engines (Gillespie-based [Dennis, Kivimäki...])
- distributed (Mamuti, Perinotti, M., 2014)

(based on various algorithms for solving matching problem)

Model checkers [Perrone 2012, MPM in progress]

Graphical editors [Fadhil, Hildebrandt]

...

## Labels from reactions

**Theorem:** in a BRS, the bisimilarity given by the LTS whose labels are defined by IPOs, is always a congruence

Hence, in order to get a LTS with a compositional bisimilarity for a process algebra:

- Encode the process algebra as a BRS
- Calculate the IPO labels

Often the resulting bisimilarity coincides with the known one

## Example: $\pi$ -calculus



**Proposition:** The bisimilarity induced by IPOs coincides with the strong early bisimilarity.

# Deriving a good LTS

Often the semantics of a process algebra is given by means of a Labelled Transition System

$$P \xrightarrow{a} Q$$

Useful for defining bisimilarity, model checking, etc.

**Problem:** how to define a good LTS for a process algebra?

*Good* = it induces a *compositional* bisimilarity

$$P \sim Q \text{ iff for all } C[\ ]: C[P] \sim C[Q]$$

In general, it is a difficult and error-prone task.  
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# Labels from contexts

In a BRS we can define labels for an agent as the *minimal* contexts (i.e. bigraphs) which are required to make a reaction

$$\frac{C[G] \rightarrow G' \quad C[ ] \text{ minimal}}{G \xrightarrow{C} G'}$$

$C[ ]$  is "what  $G$  is missing" to make a reaction

In bigraphs, minimality is formally given by the categorical notion of *idempotent pushout* (IPO).

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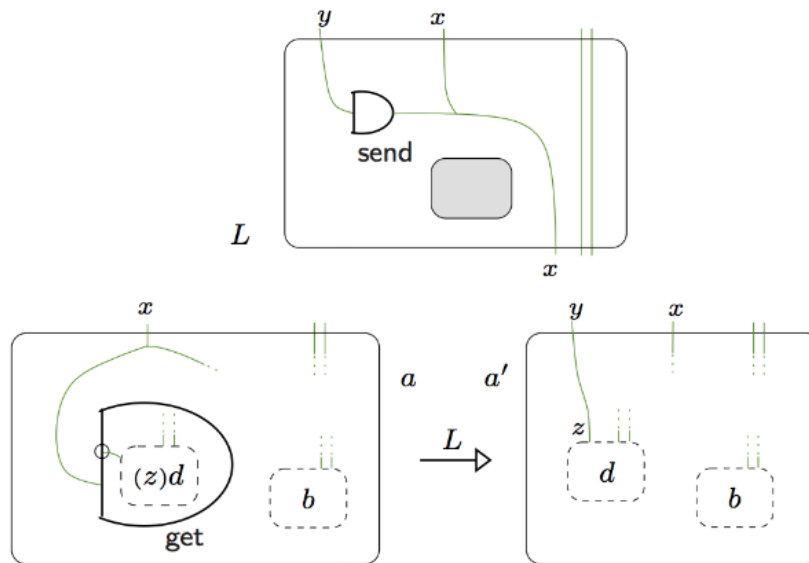
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# Example: $\pi$ -calculus

$a$	$L$	$a'$	conditions	$\bar{L}$
$/W \circ (\text{send}_{xy} \mid b)$	$\text{get}_x \mid \text{id}, (z)d \otimes \text{id}$	$a'_0$	$x \notin W, Z \cap (X \otimes W) = \emptyset, (z)d$ discrete	$\bar{x}(z)d_\pi$
$/W \circ ((\text{get}_x \circ (z)d) \mid b)$	$\text{send}_{xy} \mid \text{id}$	$a'_0$	$x \notin W, y \notin X \otimes W$	$xy$
$/W \circ (\text{send}_{xy} \mid (\text{get}_u \circ (z)d) \mid b)$	$x/u \mid \text{id}$	$(x/u \mid \text{id}) \circ a'_0$	$x, u \notin W, x \neq u$	$x/u$
$/W \circ (\text{send}_{xy} \mid (\text{get}_x \circ (z)d) \mid b)$	$\text{id}$	$a'_0$		$\tau$

where  $a'_0 = /W \circ (x \mid (y/z \circ d) \mid b)$



corresponds to  
 $x(z).D \xrightarrow{xy} D\{y/x\}$

**Proposition:** The bisimilarity induced by IPOs coincides with the strong early bisimilarity.

# Tools

Simulation tools:

- nondeterministic execution engines (BAM [Perrone et al.]
- stochastic engines (Gillespie-based [Danos, Krivine,...])
- distributed [Mansutti, Peressotti, M., 2014]

(based on various algorithms for solving matching problem)

Model checkers [Perrone 2012, MPM in progress]

Graphical editors [Faithful, Hildebrandt]

...

# LibBig: a Java Library for Bigraphs

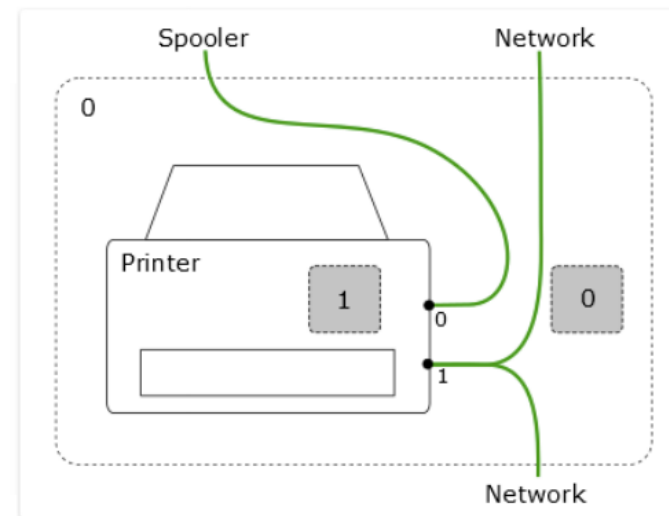
An implementation of the machinery for defining and manipulating bigraphical reactive systems.

Matching is implemented as a CSP.

Easily extensible and adaptable to other variants

<http://mads.dimi.uniud.it/wordpress/downloads/libbig/>

```
BigraphBuilder builder = new BigraphBuilder(signature);
OuterName spooler = builder.addOuterName("Spooler");
OuterName network = builder.addOuterName("Network");
Root root = builder.addRoot();
Node printer = builder.addNode("Printer",root,spooler,network);
builder.addSite(root);
builder.addSite(printer);
builder.addInnerName("Network",network);
Bigraph bigraph = builder.makeBigraph();
```





#### Bigraphs are a good operational metamodel!

- Bigraphical Reactive Systems are a general operational meta-model which can be instantiated to many models and systems
- Provides a theory of general results and tools
- Graphically oriented, yet rigorously defined in category theory
- Many ideas have been ported to other contexts (e.g. BGCs are used in PROOP categories)
- In fact, the "bigraphical way of thinking" is often used as a guideline in the design and analysis of distributed systems

# Conclusions

#### Still to come...

- General BRSS analysis using Abstract Interpretation techniques (e.g. CFA, termination, interference, ...)
- Further development of library and tools
- CTL-like spatial-temporal logic
- Applications (especially in agent-oriented programming)
- Overall, the model can evolve in different ways, so feedback is very welcome!

<http://bigraph.org>

#### Other cool stuff we had not time to see here

- Categorical formulations
- Application to bisimilarity
- Agent-based programming (Pereira et al., Marsullo et al.)
- Programming languages refinement and engineering (Penttonen et al., Grohmann et al.)
- Variants (directed, stochastic, typed, etc.)
- Generalization: multi-graphs
- Computational bigraphs (Debris & Milner)
- Spatial logic (Bilgic, Contard et al.)
- ...



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<http://bigraph.org>

# Biographical Reactive Systems

Marino Miculan  
MADS lab  
(with results by many people)

MeMo Workshop, June 6, 2014

## Statics

## Dynamics

## Metatheory & Tools

## Conclusions

### Biographical Reactive System

A discrete *reactive system* is composed by a set of states and a transition relation.

A **Biographical Reactive System** is a RS where

- States are **bigraphs**: data structures rendering explicitly the positions and connections of system's components
- State transitions are **bigraph rewritings** defined by a set of local reaction rules

So BRSS propose as an *operational* metamodel.